

# IEEE 802.11, Token Rings



# [ Medium Access Control ]

- Wireless channel is a shared medium
- Need access control mechanism to avoid interference
- Why not CSMA/CD?



# [ Ethernet MAC Algorithm ]



- Listen for carrier sense before transmitting
- Collision: What you hear is not what you sent!

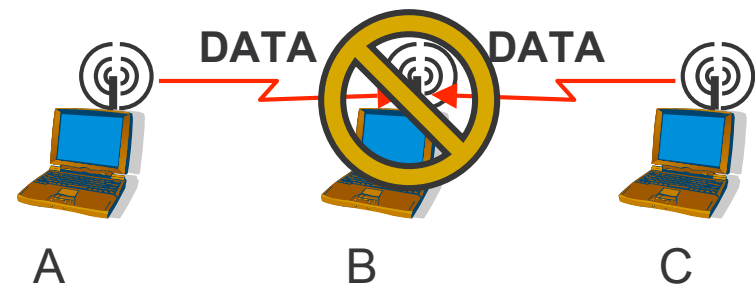
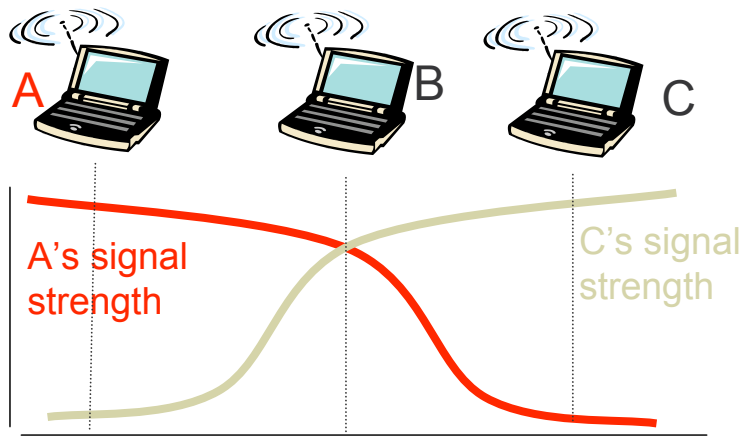
# [ CSMA/CD in WLANs? ]

- Most (if not all) radios are half-duplex
  - Listening while transmitting is not possible
- Collision might not occur at sender
  - Collision at receiver might not be detected by sender!



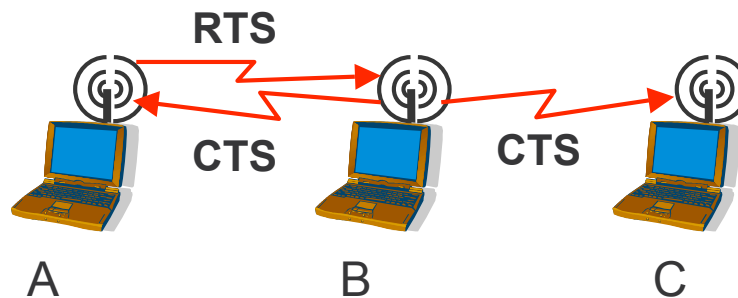
# Hidden Terminal Problem

- Node B can communicate with both A and C
- A and C cannot hear each other
- When A transmits to B, C cannot detect the transmission using the carrier sense mechanism
- If C transmits, collision will occur at node B



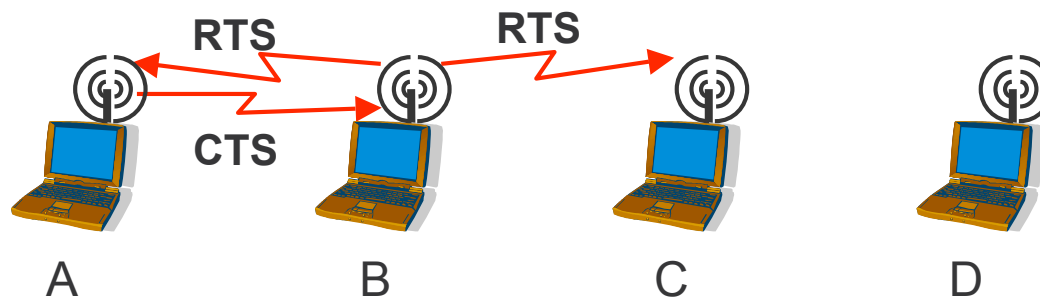
# MACA Solution for Hidden Terminal Problem

- When node A wants to send a packet to node B
  - Node A first sends a Request-to-Send (RTS) to B
- On receiving RTS
  - Node B responds by sending Clear-to-Send (CTS) to A
  - provided node B is able to receive the packet
- When a node C overhears a CTS, it keeps quiet for the duration of the transfer



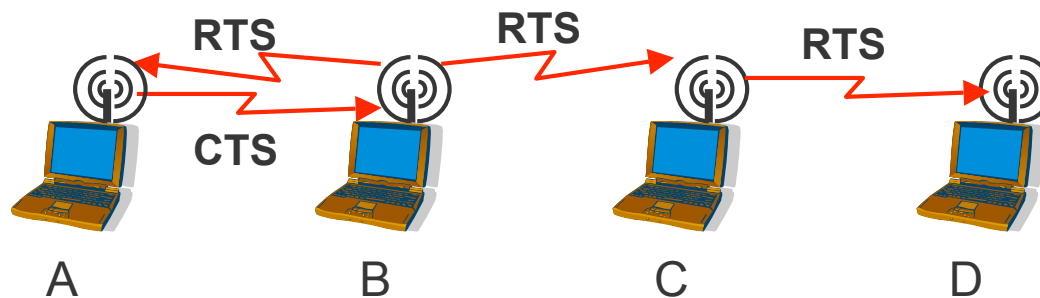
# Exposed Terminal Problem

- B talks to A
- C wants to talk to D
- C senses channel and finds it to be busy
- C stays quiet (when it could have ideally transmitted)



# MACA Solution for Exposed Terminal Problem

- Sender transmits Request to Send (RTS)
- Receiver replies with Clear to Send (CTS)
- Neighbors
  - See CTS - Stay quiet
  - See RTS, but no CTS - OK to transmit





# [ Collisions ]

- Still possible
  - RTS packets can collide!
- Binary exponential backoff
  - Backoff counter doubles after every collision and reset to minimum value after successful transmission
  - Performed by stations that experience RTS collisions
- RTS collisions not as bad as data collisions in CSMA
  - Since RTS packets are typically much smaller than DATA packets



# [ Reliability ]

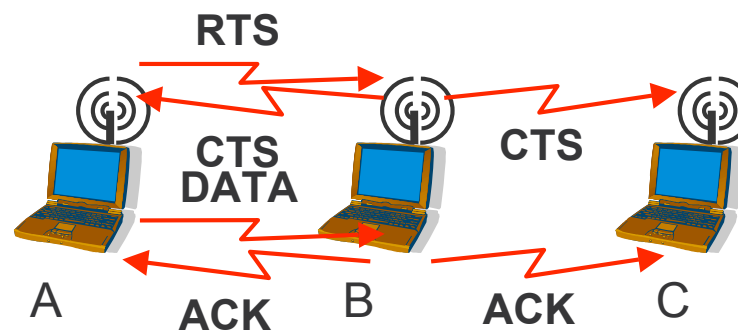
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- Wireless links are prone to errors
  - High packet loss rate detrimental to transport-layer performance
- Mechanisms needed to reduce packet loss rate experienced by upper layers



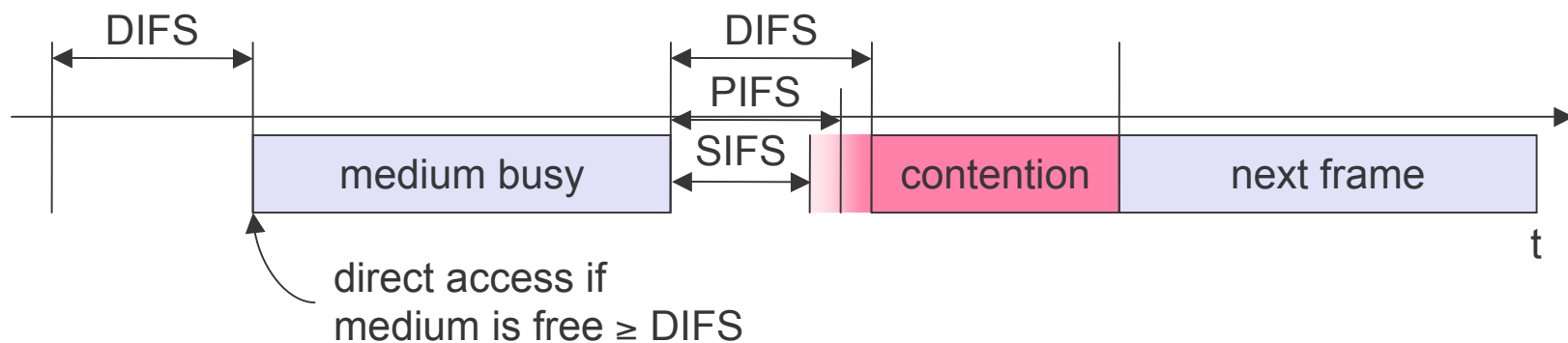
# A Simple Solution to Improve Reliability - MACAW

- When node B receives a data packet from node A, node B sends an Acknowledgement (ACK)
- If node A fails to receive an ACK
  - Retransmit the packet



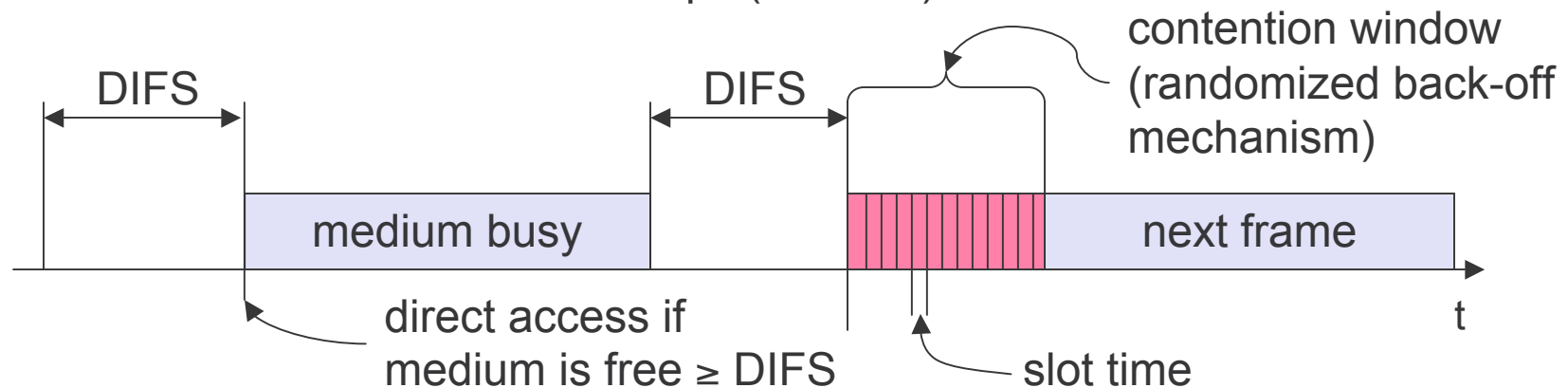
# [ Interframe Spacing ]

- Interframe spacing
  - Plays a large role in coordinating access to the transmission medium
- Varying interframe spacings
  - Creates different priority levels for different types of traffic!
- 802.11 uses 4 different interframe spacings



# IEEE 802.11 - CSMA/CA

- Sensing the medium
- If free for an Inter-Frame Space (IFS)
  - Station can start sending (IFS depends on service type)
- If busy
  - Station waits for a free IFS, then waits a random back-off time (collision avoidance, multiple of slot-time)
- If another station transmits during back-off time
  - The back-off timer stops (fairness)



# [Types of IFS]

- SIFS
  - Short interframe space
  - Used for highest priority transmissions
  - RTS/CTS frames and ACKs
- DIFS
  - DCF interframe space
  - Minimum idle time for contention-based services ( $>$  SIFS)



# [Types of IFS]

- PIFS
  - PCF interframe space
  - Minimum idle time for contention-free service ( $>$ SIFS,  $<$ DIFS)
- EIFS
  - Extended interframe space
  - Used when there is an error in transmission



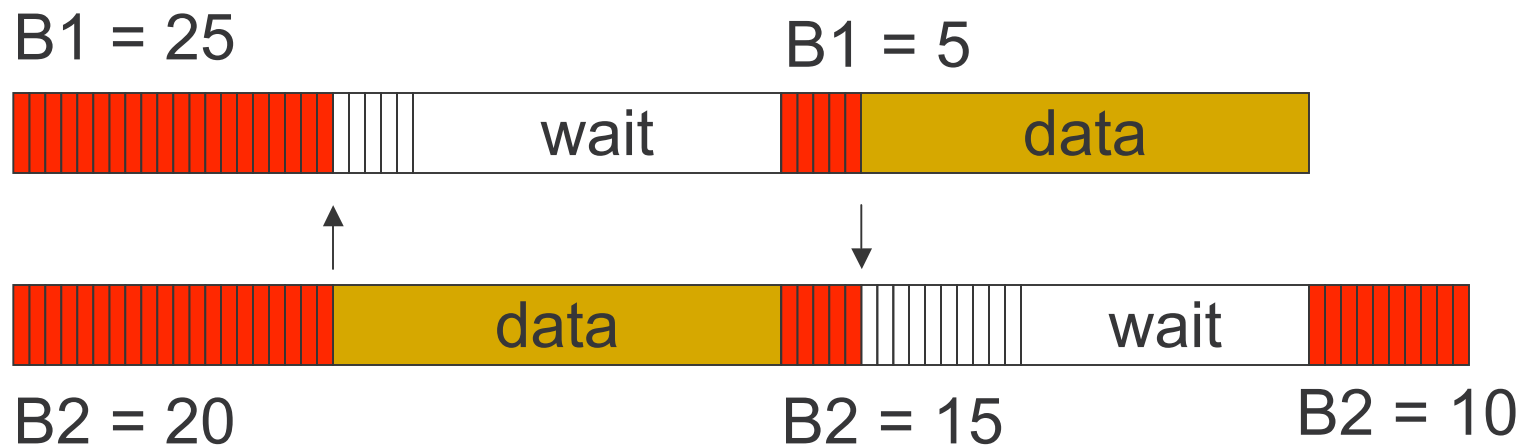
# [ Backoff Interval ]

- When transmitting a packet, choose a backoff interval in the range  $[0, cw]$ 
  - $cw$  is contention window
- Count down the backoff interval when medium is idle
  - Count-down is suspended if medium becomes busy
- When backoff interval reaches 0, transmit RTS





# [ DCF Example ]



$cw = 31$

**B1 and B2 are backoff intervals  
at nodes 1 and 2**



# [ Backoff Interval ]

- The time spent counting down backoff intervals is a part of MAC overhead
- Large cw
  - Large backoff intervals
  - Can result in larger overhead
- Small cw
  - larger number of collisions (when two nodes count down to 0 simultaneously)



# [ Backoff Interval ]

- The number of nodes attempting to transmit simultaneously may change with time
  - Some mechanism to manage contention is needed
- IEEE 802.11 DCF
  - Contention window  $cw$  is chosen dynamically depending on collision occurrence



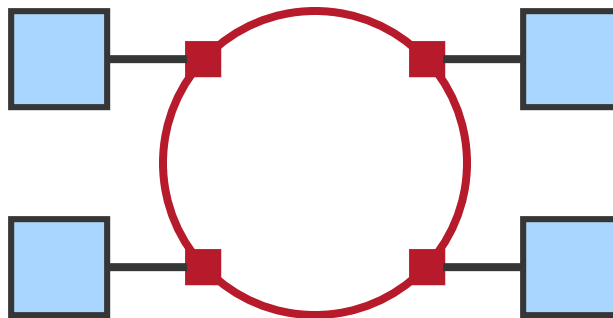
# Binary Exponential Backoff in DCF

- When a node fails to receive CTS in response to its RTS, it increases the contention window
  - cw is doubled (up to an upper bound)
- When a node successfully completes a data transfer, it restores cw to  $Cw_{\min}$ 
  - cw follows a sawtooth curve



# [Token Ring]

- Example Token Ring Networks
  - IBM: 4Mbps token ring
  - IEEE 802.5: 16Mbps



# [Token Ring]

- Focus on Fiber Distributed Data Interface (FDDI)
  - 100 Mbps
  - Was (not is) a candidate to replace Ethernet
  - Used in some MAN backbones (LAN interconnects)
- Outline
  - Rationale
  - Topologies and components
  - MAC algorithm
  - Priority
  - Feedback
  - Token management



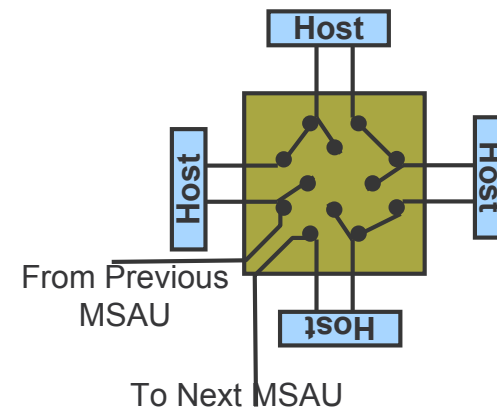
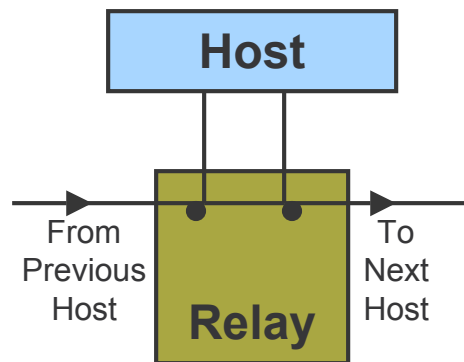
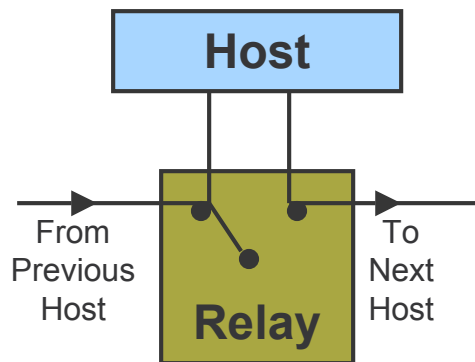
# [Token Ring]

- Why emulate a shared medium with point-to-point links?
- Why a shared medium?
  - Convenient broadcast capabilities
  - Switches costly
- Why emulation?
  - Simpler MAC algorithm
  - Fairer access arbitration
  - Fully digital (802.3 collision detection requires analog)



# Token Ring: Topology and Components

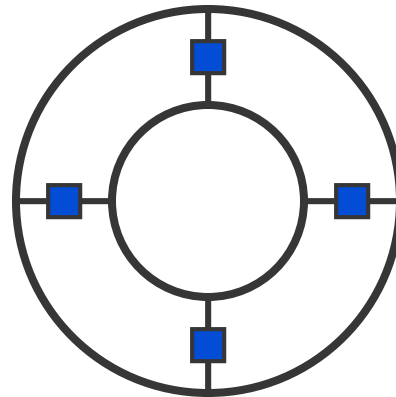
- Relay
  - Single Relay
  - Multistation access units





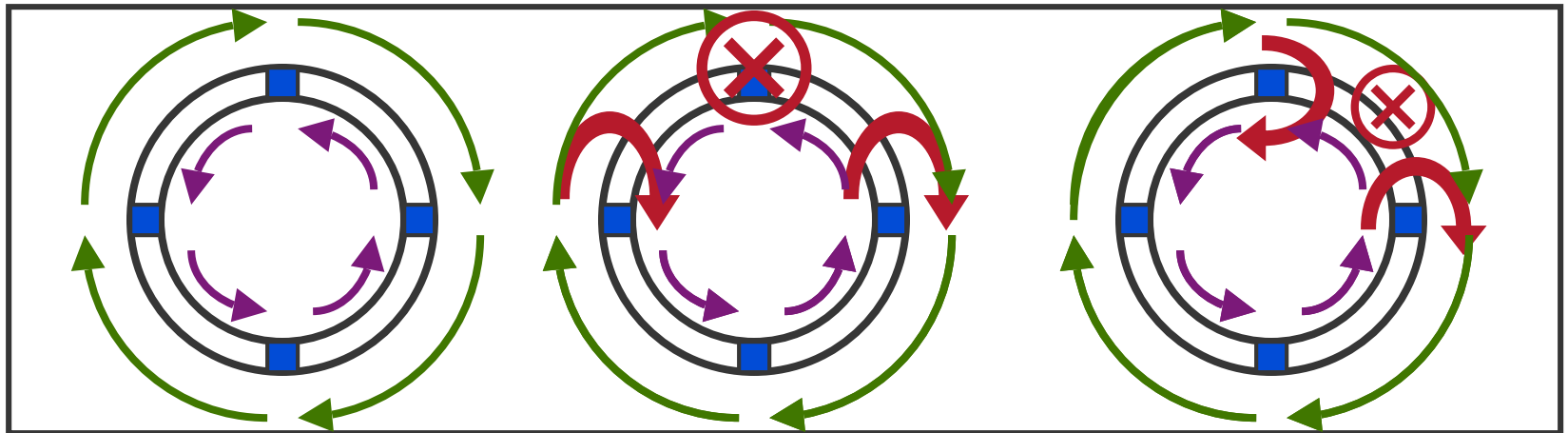
# [Token Ring: Dual Ring]

- Example Token Ring Networks
  - FDDI: 1000Mbps
    - Fiber Distributed Data Interface



# FDDI

- Dual ring configuration
  - Self-healing
    - Normal flow in green direction
    - Can detect and recover from one failure



# [ Multistation Access Unit ]

- Each station imposes a delay
  - E.g. 50 ms
- Maximum of 500 Stations
- Upper limit of 100km
  - Need 200km of fiber
- Uses 4B/5B encoding
- Can be implemented over copper



# [Token Ring: Basic Concepts]

- Frames flow in one direction
  - Upstream to downstream
- Token
  - Special bit pattern rotates around ring
- Stations
  - Must capture token before transmitting
  - Must remove frame after it has cycled
  - Must release token after transmitting
- Service
  - Stations get round-robin service

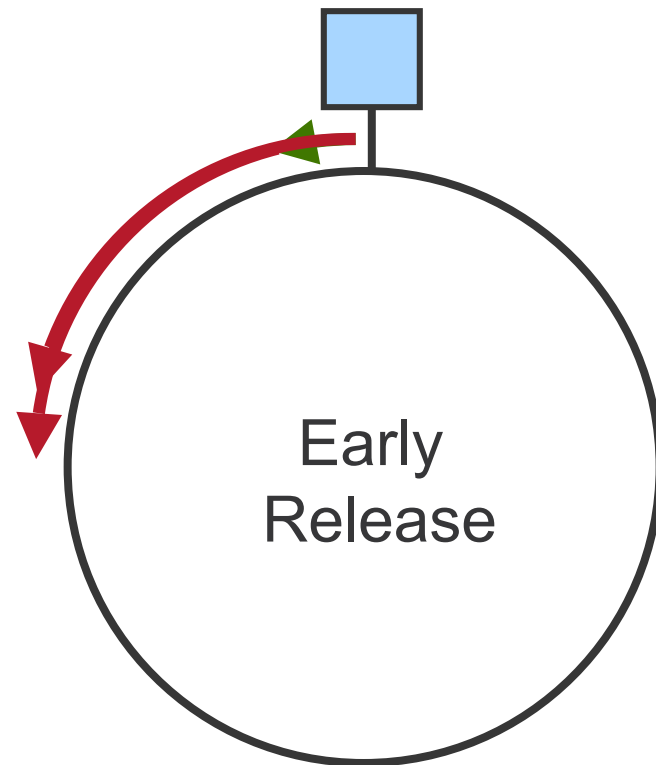
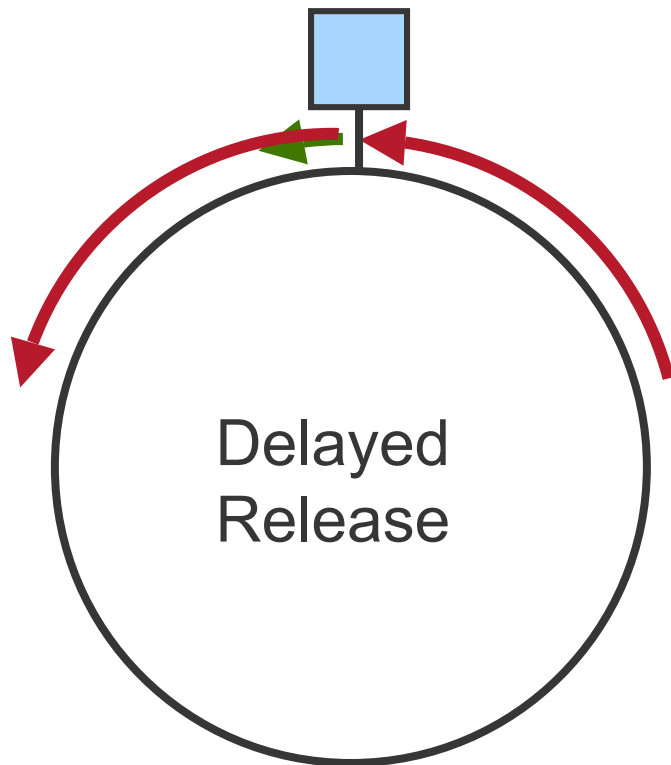


# [ Token Ring: Basic Concepts ]

- Immediate release
  - Used in FDDI
  - Token follows last frame immediately
- Delayed release
  - Used in IEEE 802.5
  - Token sent after last frame returns to sender



# [Token Release]



# Token Ring: Media Access Control Parameters

- Token Holding Time (THT)
  - Upper limit on how long a station can hold the token
  - Each station is responsible for ensuring that the transmission time for its packet will not exceed THT
- Token Rotation Time (TRT)
  - How long it takes the token to traverse the ring.
  - $TRT \leq \text{ActiveNodes} \times THT + \text{RingLatency}$
- Target Token Rotation Time (TTRT)
  - Agreed-upon upper bound on TRT



# [ 802.5 Reliability ]

- Delivery status
  - Trailer
    - A bit
      - Set by recipient at start of reception
    - C bit
      - Set by recipient on completion on reception





# [ 802.5 Monitor ]

- Responsible for
  - Inserting delay
  - Token presence
    - Should see a token at least once per TRT
  - Check for corrupted frames
  - Check for orphaned frames
    - Header
      - Monitor bit
        - Monitor station sets bit first time it sees packet
        - If monitor sees packet again, it discards packet



# [Token Maintenance: 802.5]

- Monitoring for a Valid Token
  - All stations should periodically see valid transmission (frame or token)
  - Maximum gap
    - = ring latency + max frame  $\leq$  2.5ms
  - Set timer at 2.5ms
    - send claim frame if timer expires



# [ Timing Algorithm: 802.5 ]

- Each node measures TRT between successive tokens
  - If measured-TRT  $>$  TTRT
    - Token is late
    - Don't send
  - If measured-TRT  $<$  TTRT
    - Token is early
    - OK to send
- Worse case:
  - $2 \times$ TTRT between seeing token
  - Back-to-back  $2 \times$ TTRT rotations not possible



# [ Traffic Classes: FDDI ]

- Two classes of traffic
  - Synchronous
    - Real time traffic
    - Can always send
  - Asynchronous
    - Bulk data
    - Can send only if token is early



# [ Timing Algorithm: FDDI ]

- Each station is allocated  $S_i$  time units for synchronous traffic per TRT
- TTRT is negotiated
  - $S_1 + S_2 + \dots + S_N + \text{RingLatency} \leq \text{TTRT}$
- Algorithm Goal
  - Keep actual rotation time less than TTRT
  - Allow station  $i$  to send  $S_i$  units of synchronous traffic per TRT
  - Fairly allocate remaining capacity to asynchronous traffic
  - Regenerate token if lost

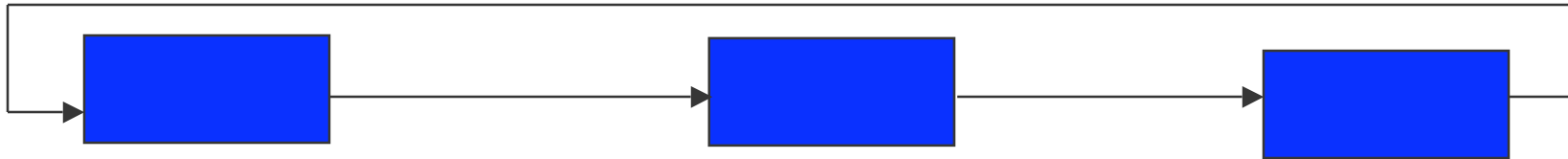


# [ Timing Algorithm: FDDI ]

- When a node gets the token
  - Set TRT = time since last token
  - Set THT = TTRT – TRT
  - If TRT > TTRT
    - Token is late
    - Send synchronous data
    - Don't send asynchronous data
  - If TRT < TTRT
    - Token is early
    - OK to send any data
      - Send synchronous data, adjust THT
      - If THT > 0, send asynchronous data



# [ FDDI example ]

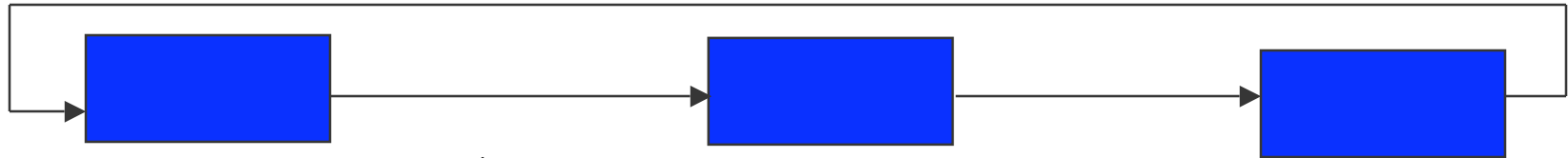


- Assume

- RingLatency=12  $\mu$ s
- Three active stations
- Each with  $S_i=20$   $\mu$ s
- TTRT=100  $\mu$ s
- Stations have unlimited supply of asynchronous traffic.



# [ FDDI example ]

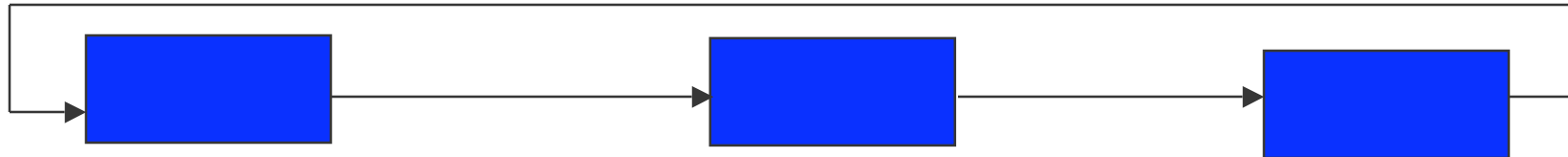


Arrival time	TRT	s/a	Arrival time	TRT	s/a	Arrival time	TRT	s/a
0	0	0/0	4	0	0/0	8	0	0/0
12	12	20/88	124	120	20/0	148	140	20/0
172	160	20/0	196	72	20/28	248	100	20/0
272	100	20/0	296	100	20/0	320	72	20/28
372	100	20/0	396	100	20/0	420	100	20/0
444	72	20/28	496	100	20/0	520	100	20/0





# [ FDDI example ]



0	0	0	0	0	0	0	0	0	0
12	12	88	124	120	0	148	140	0	
172	160	0	196	72	28	248	100	0	
272	100	0	296	100	0	320	72	28	
372	100	0	396	100	0	420	100	0	
444	72	28	496	100	0	520	100	0	
544	100	0	568	72	28	620	100	0	
644	100	0	668	100	0	692	72	28	
744	100	0	768	100	0	792	100	0	
816	72	28	868	100	0	892	100	0	
916	100	0	940	72	28	992	100	0	
1016	100	0	1040	100	0	1064	72	28	
1116	100	0	1140	100	0	1164	100	0	
1188	72	28	1240	100	0	1264	100	0	
1288	100	0	1312	72	28	1364	100	0	
1388	100	0	1412	100	0	1436	72	28	
1488	100	0	1512	100	0	1536	100	0	
1560	72	28	1612	100	0	1636	100	0	
1660	100	0	1684	72	28	1736	100	0	
1760	100	0	1784	100	0	1808	72	28	



# [ FDDI Performance ]

- Synchronous traffic may consume one TTRT worth of time
  - $TRT > TTRT$
- Worst case
  - $TRT < 2 * TTRT$
  - Any asynchronous traffic plus RingLatency  $\leq TTRT$
  - Synchronous traffic  $< TTRT$



# [ FDDI Performance ]

- Can't have two consecutive TRT =  $2 * TTRT$ 
  - After a cycle with TRT =  $2 * TTRT$ , no asynchronous traffic will be sent



# [ Token Maintenance: FDDI ]

- Lost Token
  - No token when initializing ring
  - Bit error corrupts token pattern
  - Node holding token crashes
- Monitoring for a valid token
  - Should see valid transmission (frame or token) periodically – within  $2 * TTRT$
  - Maximum gap =  $\text{RingLatency} + \text{MaxFrame} \leq 2.5\text{ms}$

